Verifying Software Transactions

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Outline

- Concurrency control with non-blocking transactions (review)
- Introduction to the Spin Model Checker
- Modelling a software transaction implementation
- Conclusions
Non-blocking Transactions
Transactions (review)

- A transaction is a sequence of loads and stores that either commits or aborts.
- If a transaction commits, all the loads and stores appear to have executed atomically.
- If a transaction aborts, none of its stores take effect.
- Transaction operations aren’t visible until they commit or abort.
Non-blocking synchronization

- Although transactions can be implemented with mutual exclusion (locks), we are interested only in **non-blocking** implementations.
- In a non-blocking implementation, the failure of one process cannot prevent other processes from making progress. This leads to:
  - **Scalable parallelism**
  - **Fault-tolerance**
  - **Safety**: freedom from some problems which require careful bookkeeping with locks, including priority inversion and deadlocks.
- Little known requirement: limits on transaction suicide.
Non-blocking algorithms are hard!

- In published work on Synthesis, a non-blocking operating system implementation, three separate races were found:
  - One **ABA problem** in LIFO stack.
  - One **likely race** in MP-SC FIFO queue.
  - One **interesting corner case** in quajeck callback handling.
- It’s hard to get these right! Ad hoc reasoning doesn’t cut it.
The Spin Model Checker
The Spin Model Checker

- Spin is a model checker for communicating concurrent processes. It checks:
  - Safety/termination properties.
  - Liveness/deadlock properties.
  - Path assertions (requirements/never claims).
- It works on finite models, written in the Promela language, which describe infinite executions.
- Explores the entire state space of the model, including all possible concurrent executions, verifying that Bad Things don’t happen.
- Not an absolute proof — but pretty useful in practice.
Dekker’s mutex algorithm (C)

```c
int turn;
int wants[2];

// i is the current thread, j=1-i is the other thread
while(1) { // trying
    wants[i] = TRUE;
    while (wants[j]) {
        if (turn==j) {
            wants[i] = FALSE;
            while (turn==j) ; // empty loop
            wants[i] = TRUE;
        }
    }
    critical_section();
    turn=j; // release
    wants[i] = FALSE;
    noncrit();
}
```
Railroad visualization of Dekker’s algorithm for mutual exclusion. The threads “move” in the direction shown by the arrows. [from lecture 5 scribe notes]
Dekker’s mutex algorithm (Promela)

```c
bool turn, flag[2]; byte cnt;
active [2] proctype mutex() /* Dekker’s 1965 algorithm */
{
    pid i, j;
    i = _pid;
    j = 1 - _pid;

    flag[i] = true;
    do /* can be 'if' – says Doran&Thomas */
    :: flag[j] ->
        if
            :: turn == j ->
                flag[i] = false;
                !(turn == j);
                flag[i] = true
            :: else
                fi
        :: else -> break
    od;

cnt++; assert(cnt == 1); cnt--; /* critical section */
    turn = j;
    flag[i] = false;
    goto again
}
```
Spin verification

$ spin -a mutex.pml
$ cc -DSAFETY -o pan pan.c
$ ./pan
(Spin Version 4.1.0 -- 6 December 2003)
  + Partial Order Reduction

Full statespace search for:
  never claim               -  (none specified)
  assertion violations      +
  cycle checks               -  (disabled by -DSAFETY)
  invalid end states        +

State-vector 20 byte, depth reached 65, errors: 0
  190 states, stored
  173 states, matched
  363 transitions (= stored+matched)
  0 atomic steps
hash conflicts: 0 (resolved)
(max size 2^18 states)
$
If an error is found, will give you execution trail producing the error.
Spin theory

- Generates a Büchi Automaton from the Promela specification.
  - Finite-state machine w/ special acceptance conditions.
  - Transitions correspond to executability of statements.
- Depth-first search of state space, with each state stored in a hashtable to detect cycles and prevent duplication of work.
  - If $x$ followed by $y$ leads to the same state as $y$ followed by $x$, will not re-traverse the succeeding steps.
- If memory is not sufficient to hold all states, may ignore hashtable collisions: requires one bit per entry. # collisions provides approximate coverage metric.
Modeling software transactions
A software transaction implementation

• Goals:
  • Non-transactional operations should be fast.
  • Reads should be faster than writes.
  • Minimal amount of object bloat.

• Solution:
  • Use special \texttt{FLAG} value to indicate “location involved in a transaction”.
  • Object points to a linked list of \texttt{versions}, containing values written by (in-progress, committed, or aborted) transactions.
  • Semantic value of a \texttt{FLAGged} field is: “value of the first version owned by a committed transaction on the version list.”
Transactions using version lists

Object #1

MyClass

- type

- versions

(TID68)

-readers

FLAG

- field1

- field2

3.14159

2.71828

Version

- owner

- next

Transaction ID #68

WAITING

status

Transaction ID #56

COMMITTED

status

Transaction ID #23

COMMITTED

status

Version

- owner

- next

Version

- owner

- next

Object #2

OtherClass

- type

- versions

(TID25)

-readers

2.71828

FLAG

- field1

- field2

'A'

'B'

Ananian, 6.895 – p. 16
Races, races, everywhere!

- Lots of possible races:
  - What if two threads try to `FLAG` a field at the same time?
  - What if two threads try to copy-back a `FLAGged` field at the same time?
  - What if two transactions perform conflicting updates?
  - Do transactions commit atomically?

- Formulated model in Promela and used Spin to verify correctness.
  - Used the 16G on memory on `yggdrasil` to good advantage.
Non-transactional Read

inline readNT(o, f, v) {
    do
        :: v = object[o].field[f];
        if
            :: (v!=FLAG) -> break /* done! */
            :: else
                fi;
        copyBackField(o, f, kill_writers, _st);
        if
            :: (_st==false_flag) ->
                v = FLAG;
                break
            :: else
                fi
        od
    }
}
Non-transactional Write

```c
inline writeNT(o, f, nval) {
    if
        :: (nval != FLAG) ->
            do
                :: atomic {
                    if /* this is a LL(readerList)/SC(field) */
                        :: (object[o].readerList == NIL) ->
                            object[o].fieldLock[f] = _thread_id;
                            object[o].field[f] = nval;
                            break /* success! */
                        :: else /* success! */
                    fi
                }
                /* unsuccessful SC */
                copyBackField(o, f, kill_all, _st)
            od
        :: else -> /* create false flag */
            /* implement this as a short *transactional* write. */
            /* start a new transaction, write FLAG, commit the transaction,
             * repeat until successful. Implementation elided. */
            fi;
}
```
inline copyBackField(o, f, mode, st) {
    _nonceV=NIL; _ver = NIL; _r = NIL; st = success;
    /* try to abort each version. When abort fails, we've got a
     * committed version. */
    do
        :: _ver = object[o].version;
        if
            :: (_ver==NIL) ->
                st = saw_race; break /* Someone's done the copyback for us */
            :: else
                fi;
        /* Move owner to local var to avoid races (owner set to NIL behind
         * our back) */
        _tmp_tid=version[_ver].owner;
        tryToAbort(_tmp_tid);
        if
            :: (_tmp_tid==NIL || transid[_tmp_tid].status==committed) ->
                break /* Found a committed version */
            :: else
                fi;
        /* Link out an aborted version */
        assert(transid[_tmp_tid].status==aborted);
        CAS_Version(object[o].version, _ver, version[_ver].next, _);
    od;
}
Copy-back Field, part II

/* okay, link in our nonce. this will prevent others from doing the
 * copyback. */
if :: (st==success) ->
    assert (_ver!=NIL);
    allocVersion(_retval, _nonceV, aborted_tid, _ver);
    CAS_Version(object[o].version, _ver, _nonceV, _cas_stat);
if :: (!_cas_stat) ->
    st = saw_race_cleanup
:: else
fi
:: else
fi;

continued...
Copy-back Field, part III

/* check that no one’s beaten us to the copy back */
if :: (st==success) ->
  if :: (object[o].field[f]==FLAG) ->
    _val = version[_ver].field[f];
    if :: (_val==FLAG) -> /* false flag... */
      st = false_flag /* ...no copy back needed */
    :: else -> /* not a false flag */
      d_step { /* LL/SC */
        if :: (object[o].version == _nonceV) ->
          object[o].fieldLock[f] = _thread_id;
          object[o].field[f] = _val;
        :: else /* hmm, fail. Must retry. */
          st = saw_race_cleanup /* need to clean up nonce */
        fi
      }
    fi
  :: else /* may arrive here because of readT, which doesn’t set _val=FLAG*/
    st = saw_raceCleanup /* need to clean up nonce */
  fi
:: else /* !success */
fi;

continued...
/* always kill readers, whether successful or not. This ensures that we make progress if called from writeNT after a readNT sets readerList non-null without changing FLAG to _val (see immediately above; st will equal saw_race_cleanup in this scenario). */

if (mode == kill_all) ->
  do /* kill all readers */
    moveReaderList(_r, object[o].readerList);
    if
      (_r==NIL) -> break
    else
      fi;
  tryToAbort(readerlist[_r].transid);
  /* link out this reader */
  CAS_Reader(object[o].readerList, _r, readerlist[_r].next, _);
  od;
else /* no more killing needed. */
  fi;
/* done */
}

done!
Conclusions
Conclusions

- Non-blocking transactions are a useful and intuitive means of concurrency control.
- Software implementations of non-blocking transactions are possible and may be efficient, but hard to get right!
- The Spin model checking tool is an excellent way to nail down indeterminacies in parallel code and more rigorously show correctness.